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CHAPTER 1.

1.5 Linearization of the  
valve shows that  
 $\dot{v} = 4v^3 u$ .

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$D(q^{-1}) A(q^{-1})$

$[T(t)(\tilde{t} + 1)]$

(3.161) and the

parameter adaptation



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algorithm satisfying

the passivity condition

will take the form:  $\hat{y}(t+1) = \hat{y}(t) + F(e(t))e(t+1)$

(3.162) The equivalent

feedback

representation

associated with the

output error predictor

using the above PAA

is shown in Fig. 3.9.

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