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x(˜)d˜ where T>0 is the averaging interval, x(t) and y(t) are the system input and output. i.Determine if the averager is a linear system. ii.Let T = 1, x(t) = u(t), calculate and plot the corresponding output, delay then the input to get x(t 2) = u(t 2), and calculate and plot the corresponding output.

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